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Understanding and Using the Controller Area Network Communication Protocol A Comprehensible Guide to Controller Area Network CAN - Controller Area Network Controller Area Network Controller Area Network Prototyping With Arduino Data Acquisition from HD Vehicles Using J1939 CAN Bus Handbook of Networked and Embedded Control Systems Embedded Networking with CAN and CANopen CAN System Engineering Microcontroller and Smart Home Networks Controller Area Network Projects Multiplexed Networks for Embedded Systems Automotive Ethernet Industrial Sensors and Controls in Communication Networks Sae J1939 ECU Programming & Vehicle Bus Simulation with Arduino Embedded Systems and Artificial Intelligence A Comprehensible Guide to J1939 Can and Fpga Communication Engineering Embedded Systems Handbook FlexRay and its Applications Hacking Connected Cars Controller Area Network A Controller Area Network Gateway to ZigBee Occupational Outlook Handbook GNU/Linux Rapid Embedded Programming Inter- and Intra-Vehicle Communications Automotive Embedded Systems Handbook Implementation of Controller Area Network (CAN) Bus in an Autonomnous [sic] All-terrain Vehicle Understanding and Using the Controller Area Network Communication Protocol MSP430 Microcontroller Basics Time-Triggered Communication Innovative Mobile and Internet Services in Ubiquitous Computing Advanced Manufacturing and Automation IX Introduction to Storage Area Networks Automotive Ethernet Advances in Computing, Communication and Control The Car Hacker's Handbook Modbus Information Networking General Standardization of CAN (controller Area Network) Bus Protocol for Airborne Use

Controller Area Network (CAN) is a vehicle bus standard protocol designed specially for automotive application. ECUs (Electronic control units) within vehicle can communicate with each other using CAN Bus standard protocol. It is high speed, bandwidth efficient network. In order to reduce point to point wiring harness in vehicle automation, CAN is suggested as a means for data communication within the vehicle environment. The benefits of CAN bus based network over traditional point to point schemes will offer increased flexibility and expandability. This book includes proceedings of the 15th International Conference on Innovative Mobile and Internet Services in Ubiquitous Computing (IMIS-2021), which took place in Asan, Korea, on July 1-3, 2021. With the proliferation of wireless technologies and electronic devices, there is a fast-growing interest in Ubiquitous and Pervasive Computing (UPC). The UPC enables to create a human-oriented computing environment where computer chips are embedded in everyday objects and interact with physical world. Through UPC, people can get online even while moving around, thus, having almost permanent access to their preferred services. With a great potential to revolutionize our lives, UPC also poses new research challenges. The aim of the book is to provide the latest research findings, methods, development techniques, challenges, and solutions from both theoretical and practical perspectives related to UPC with an emphasis on innovative, mobile, and Internet services. A field manual on contextualizing cyber threats, vulnerabilities, and risks to connected cars through penetration testing and risk assessment Hacking Connected Cars deconstructs the tactics, techniques, and procedures (TTPs) used to hack into connected cars and autonomous vehicles to help you identify and mitigate vulnerabilities affecting cyber-physical vehicles. Written by a veteran of risk management and penetration testing of IoT devices and connected cars, this book provides a detailed account of how to perform penetration testing, threat modeling, and risk assessments of telematics control units and infotainment systems. This book demonstrates how vulnerabilities in wireless networking, Bluetooth, and GSM can be exploited to affect confidentiality, integrity, and availability of connected cars. Passenger vehicles have experienced a massive increase in connectivity over the past five years, and the trend will only continue to grow with the expansion of The Internet of Things and increasing consumer demand for always-on connectivity. Manufacturers and OEMs need the ability to push updates without requiring service visits, but this leaves the vehicle’s systems open to attack. This book examines the issues in depth, providing cutting-edge preventative tactics that security practitioners, researchers, and vendors can use to keep connected cars safe without sacrificing connectivity. Perform penetration testing of infotainment systems and telematics control units through a step-by-step methodical guide Analyze risk levels surrounding vulnerabilities and threats that impact confidentiality, integrity, and availability Conduct penetration testing using the same tactics, techniques, and procedures used by hackers From relatively small features such as automatic parallel parking, to completely autonomous self-driving cars—all connected systems are vulnerable to attack. As connectivity becomes a way of life, the need for security expertise for in-vehicle systems is becoming increasingly urgent. Hacking Connected Cars provides practical, comprehensive guidance for keeping these vehicles secure. An authoritative yet highly accessible guide to the design and operation of the FlexRay bus, the latest protocol for automotive network communications A translation of the French edition, originally published in January 2011, this work is the result of numerous training courses that Dominique Paret has given in companies, and it provides detailed explanations of the design and operation of the FlexRay bus. Comprised of five parts the book covers: the FlexRay concept and its communication protocol; the FlexRay physical layer; synchronization and global time and; architecture of a node, components and development aid tools for hardware and software. Provides comprehensive treatment of the FlexRay network, including its implementation through a real automotive application Includes the latest specifications (Version 3) concluded by the FlexRay consortium widely expected to become the industry standard Written by an author with in-depth experience of automotive electronics, including FlexRay, and presenter of specialist training courses to the industry Includes a review of industrial tools to help design and implement a FlexRay based distributor application This book gathers selected research papers presented at the First International Conference on Embedded Systems and Artificial Intelligence (ESAI 2019), held at Sidi Mohamed Ben Abdellah University, Fez, Morocco, on 2–3 May 2019. Highlighting the latest innovations in Computer Science, Artificial Intelligence, Information Technologies, and Embedded Systems, the respective papers will encourage and inspire researchers, industry professionals, and policymakers to put these methods into practice. In smart home automation, several common smart home automation protocols that allow different devices to speak and communicate together have appeared during the last few decades. Some of the smart home protocols come under the umbrella of what is called the "Internet of Things (IoT)". The proposed protocols can be grouped into wired networks e.g. X10, UPB; wireless or radio networks as ZigBee, Z-Wave, Bluetooth; or dual (wired and radio) such as Insteon. This book introduces the reader to some of the most popular microcontroller and smart home networks. Controller Area Network is employed widely in modern automobiles, medical instrumentation, building automation, and manufacturing control systems. DeviceNet is one example of a commercial SCADA network that is based on the CAN specification. Commercially known as "ZigBee," the IEEE 802.15.4 wireless standard is designed to operate at low data rates with secure, low cost network configurations. Two key elements of the standard are low power operation and inherent security implementation. This work proposes an architecture to extend CAN to the wireless domain of IEEE 802.15.4, thereby providing a low cost, low power, efficient, and secure wireless network interface compatible with many existing SCADA infrastructure networks, in addition to the countless other installations incorporating a CAN backbone. An architectural model for such an extension mechanism is proposed which includes additions to the CAN protocol stack. New protocols are recommended for the tunneling of messages and for enhancing reliability. This work is directed towards developers of products involving CAN and 802.15.4, as well as researchers in the field of wireless personal area networks. Controller Area Network (CAN) is a serial network technology that was originally designed for the automotive industry, but has also become a popular bus in industrial automation. The CAN bus is primarily used in embedded solutions and provides communication among microprocessors up to

real-time requirements. A Comprehensible Guide To Controller Area Network represents a very thoroughly researched and complete work on CAN. It provides information on all CAN features and aspects combined with high level of readability. Book jacket. An annotated guide to program and develop GNU/Linux Embedded systems quickly About This Book Rapidly design and build powerful prototypes for GNU/Linux Embedded systems Become familiar with the workings of GNU/Linux Embedded systems and how to manage its peripherals Write, monitor, and configure applications quickly and effectively, manage an external micro-controller, and use it as co-processor for real-time tasks Who This Book Is For This book targets Embedded System developers and GNU/Linux programmers who would like to program Embedded Systems and perform Embedded development. The book focuses on quick and efficient prototype building. Some experience with hardware and Embedded Systems is assumed, as is having done some previous work on GNU/Linux systems. Knowledge of scripting on GNU/Linux is expected as well. What You Will Learn Use embedded systems to implement your projects Access and manage peripherals for embedded systems Program embedded systems using languages such as C, Python, Bash, and PHP Use a complete distribution, such as Debian or Ubuntu, or an embedded one, such as OpenWrt or Yocto Harness device driver capabilities to optimize device communications Access data through several kinds of devices such as GPIO's, serial ports, PWM, ADC, Ethernet, WiFi, audio, video, I2C, SPI, One Wire, USB and CAN Practical example usage of several devices such as RFID readers, Smart card readers, barcode readers, z-Wave devices, GSM/GPRS modems Usage of several sensors such as light, pressure, moisture, temperature, infrared, power, motion In Detail Embedded computers have become very complex in the last few years and developers need to easily manage them by focusing on how to solve a problem without wasting time in finding supported peripherals or learning how to manage them. The main challenge with experienced embedded programmers and engineers is really how long it takes to turn an idea into reality, and we show you exactly how to do it. This book shows how to interact with external environments through specific peripherals used in the industry. We will use the latest Linux kernel release 4.4.x and Debian/Ubuntu distributions (with embedded distributions like OpenWrt and Yocto). The book will present popular boards in the industry that are user-friendly to base the rest of the projects on - BeagleBone Black, SAMA5D3 Xplained, Wandboard and system-on-chip manufacturers. Readers will be able to take their first steps in programming the embedded platforms, using C, Bash, and Python/PHP languages in order to get access to the external peripherals. More about using and programming device driver and accessing the peripherals will be covered to lay a strong foundation. The readers will learn how to read/write data from/to the external environment by using both C programs or a scripting language (Bash/PHP/Python) and how to configure a device driver for a specific hardware. After finishing this book, the readers will be able to gain a good knowledge level and understanding of writing, configuring, and managing drivers, controlling and monitoring applications with the help of efficient/quick programming and will be able to apply these skills into real-world projects. Style and approach This practical tutorial will get you quickly prototyping embedded systems on GNU/Linux. This book uses a variety of hardware to program the peripherals and build simple prototypes. This book constitutes the refereed proceedings of the International Conference on Advances in Computing Communications and Control, ICAC3 2011, held in Mumbai, India, in January 2011. The 84 revised full papers presented were carefully reviewed and selected from 309 submissions. The papers address issues such as AI, artificial neural networks, computer graphics, data warehousing and mining, distributed computing, geo information and statistical computing, learning algorithms, system security, virtual reality, cloud computing, service oriented architecture, semantic web, coding techniques, modeling and simulation of communication systems, network architecture, network protocols, optical fiber/microwave communication, satellite communication, speech/image processing, wired and wireless communication, cooperative control, and nonlinear control, process control and instrumentation, industrial automation, controls in aerospace, robotics, and power systems. This informative text/reference presents a detailed review of the state of the art in industrial sensor and control networks. The book examines a broad range of applications, along with their design objectives and technical challenges. The coverage includes fieldbus technologies, wireless communication technologies, network architectures, and resource management and optimization for industrial networks. Discussions are also provided on industrial communication standards for both wired and wireless technologies, as well as for the Industrial Internet of Things (IIoT). Topics and features: describes the FlexRay, CAN, and Modbus fieldbus protocols for industrial control networks, as well as the MIL-STD-1553 standard; proposes a dual fieldbus approach, incorporating both CAN and ModBus fieldbus technologies, for a ship engine distributed control system; reviews a range of industrial wireless sensor network (IWSN) applications, from environmental sensing and condition monitoring, to process automation; examines the wireless networking performance, design requirements, and technical limitations of IWSN applications; presents a survey of IWSN commercial solutions and service providers, and summarizes the emerging trends in this area; discusses the latest technologies and open challenges in realizing the vision of the IIoT, highlighting various applications of the IIoT in industrial domains; introduces a logistics paradigm for adopting IIoT technology on the Physical Internet. This unique work will be of great value to all researchers involved in industrial sensor and control networks, wireless networking, and the Internet of Things. This book to offers a hands-on guide to designing, analyzing and debugging a communication infrastructure based on the Controller Area Network (CAN) bus. Although the CAN bus standard is well established and currently used in most automotive systems, as well as avionics, medical systems and other devices, its features are not fully understood by most developers, who tend to misuse the network. This results in lost opportunities for better efficiency and performance. These authors offer a comprehensive range of architectural solutions and domains of analysis. It also provides formal models and analytical results, with thorough discussion of their applicability, so that it serves as an invaluable reference for researchers and students, as well as practicing engineers. A Clear Outline of Current Methods for Designing and Implementing Automotive Systems Highlighting requirements, technologies, and business models, the Automotive Embedded Systems Handbook provides a comprehensive overview of existing and future automotive electronic systems. It presents state-of-the-art methodological and technical solutions in the areas of in-vehicle architectures, multipartner development processes, software engineering methods, embedded communications, and safety and dependability assessment. Divided into four parts, the book begins with an introduction to the design constraints of automotive-embedded systems. It also examines AUTOSAR as the emerging de facto standard and looks at how key technologies, such as sensors and wireless networks, will facilitate the conception of partially and fully autonomous vehicles. The next section focuses on networks and protocols, including CAN, LIN, FlexRay, and TTCAN. The third part explores the design processes of electronic embedded systems, along with new design methodologies, such as the virtual platform. The final section presents validation and verification techniques relating to safety issues. Providing domain-specific solutions to various technical challenges, this handbook serves as a reliable, complete, and well-documented source of information on automotive embedded systems. The PC revolution, the advent of PDAs, and growth in the use of wireless LANs have changed the way we live our lives. Next on the horizon is the application of new technologies that will change the way we drive our cars. De rigeur for many drivers, electronic passes and GPS systems represent the tip of the iceberg in terms of emerging applications "The scope of this document characterizes access and data flow relative to CAN [Controller Area Network] and certain aspects of the data flow across the network boundaries."--Introduction, page 1. Considered a standard industry resource, the Embedded Systems Handbook provided researchers and technicians with the authoritative information needed to launch a wealth of diverse applications, including those in automotive electronics, industrial automated systems, and building automation and control. Now a new resource is required to report on current developments and provide a technical reference for those looking to move the field forward yet again. Divided into two volumes to accommodate this growth, the Embedded Systems Handbook, Second Edition presents a comprehensive view on this area of computer engineering with a currently appropriate emphasis on developments in networking and applications. Those experts directly involved in the creation and evolution of the ideas and technologies presented offer tutorials, research surveys, and technology overviews that explore cutting-edge developments and deployments and identify potential trends. This first self-contained volume of the handbook, Embedded Systems Design and Verification, is divided into three sections. It begins with a brief introduction to embedded systems design and

verification. It then provides a comprehensive overview of embedded processors and various aspects of system-on-chip and FPGA, as well as solutions to design challenges. The final section explores power-aware embedded computing, design issues specific to secure embedded systems, and web services for embedded devices. Those interested in taking their work with embedded systems to the network level should complete their study with the second volume: Network Embedded Systems. This book presents selected papers from the 9th International Workshop of Advanced Manufacturing and Automation (IWAMA 2019), held in Plymouth, UK, on November 21–22, 2019. Discussing topics such as novel techniques for manufacturing and automation in Industry 4.0 and smart factories, which are vital for maintaining and improving economic development and quality of life, it offers researchers and industrial engineers insights into implementing the concepts and theories of Industry 4.0, in order to effectively respond to the challenges posed by the 4th industrial revolution and smart factories. The Controller Area Network (CAN), invented by Bosch in 1983, is a serial field bus protocol which was originally used in road vehicles and now is widely applied in other industrial fields. Since its birth automotive electronic engineers have been use Microcontrollers (MCU) to control the CAN bus. Today, as the Field-programmable Gate Array (FPGA) has become very advance, this book introduces a new method which uses an FPGA and a MCU jointly instead of a single MCU is to design a CAN bus measurement system. Furthermore the designed system should be able to work at the fastest possible speed. Chapter 1 of this book is the introduction which includes the background, objective and outline of this book. Chapter 2 describes the CAN protocol development history and fundamentals such as application field, architecture layers, different frame structures, frame coding, error handling and fault confinement which are extracted from the CAN Specification 2.0 and ISO 11898. It helps reader to understand the CAN. Chapter 3 studies the effective data transmission rate and ratio of the CAN bus and the MCU serial UART port. Then it compares their values and draws a conclusion. This chapter is the most important theory research of this book. Chapter 4 describes the devices used in the experiments of the book. There are five major devices applied: an Altera FPGA, a 5-3.3 V level translator, an Atmel CAN MCU, a NI CAN USB and a PC with LabVIEW environment. Chapter 5 demonstrates the software development procedure for the whole system including FPGA with Quartus II, MCU with Keil C51, and NI CAN BUS with LabVIEW. Chapter 6 describes the testing experiments of the measurement system. It analyses a common error ignored during the MCU programming and shows how to solve it. After the reprogramming, three tests and their results are illustrated. Chapter 7 presents the final conclusion of this book which is that the measurement system designed here maximally utilizes the CAN effective data CAN (Controller Area Network) is a serial communication protocol that was originally developed for the automobile industry. CAN is far superior to conventional serial technologies such as RS232 in regards to functionality and reliability and yet CAN implementations are more cost effective. CANopen, a higher layer protocol based on CAN, provides the means to apply the ingenious CAN features to a variety of industrial-strength applications. Many users, for example in the field of medical engineering, opted for CANopen because they have to meet particularly stringent safety requirements. Similar requirements had to be considered by manufacturers of other equipment with very high safety or reliability requirements (e.g. robots, lifts and transportation systems). Providing a detailed look at both CAN and CANopen, this book examines those technologies in the context of embedded networks. There is an overview of general embedded networking and an introduction to the primary functionality provided by CANopen. Everything one needs to know to configure and operate a CANopen network using off-the-shelf components is described, along with details for those designers who want to build their own CANopen nodes. The wide variety of applications for CAN and CANopen is discussed, and instructions in developing embedded networks based on the protocol are included. In addition, references and examples using MicroCANopen, PCANopen Magic, and Vector's high-end development tools are provided. SAE J1939 has become the accepted industry standard and the vehicle network technology of choice for off-highway machines. This resource provides profound information on the J1939 message format and network management. Featuring a foreword by Bob Metcalfe, inventor of Ethernet! Ethernet, the most widely-used local area networking technology in the world, is moving from the server rooms of automobile manufacturers to their vehicles. As the quantity and variety of electronic devices in cars continues to grow, Ethernet promises to improve performance and enable increasingly powerful and useful applications in vehicles. Now, from Intrepid Control Systems (www.intrepidcs.com) - a leader in the world of automotive networking and diagnostic tools - comes the first book to describe the technology behind the biggest revolution in automotive networking since the 1980s: Automotive Ethernet - The Definitive Guide describes the fundamentals of networking, data link and physical layers of industry-standard Ethernet variants, as well as the new (one twisted pair 100Base Ethernet) 1TPCE or BroadR-Reach technology developed by Broadcom specifically for vehicle use. Topics covered include: in-vehicle networking requirements, comparing Ethernet to CAN and other existing networks (such as LIN, MOST, and FlexRay), TCP/UDP, IPv4/IPv6 and Diagnostics over IP (DoIP). Also covered are the Audio Video Bridging standards used to transport media over Ethernet: Stream Reservation Protocol or SRP (802.1Qat), Forward-Queueing and Time-Sensitive Streams or FQTSS (802.1Qav), Timing and Synchronization for Time-Sensitive Applications or gPTP (802.1as), and Transport Protocol for Time-Sensitive Applications or AVTP (IEEE 1722), and more. Automotive Ethernet: The Definitive Guide will also be available as an ebook for your Kindle! The Controller Area Network (CAN) was originally developed to be used as a vehicle data bus system in passenger cars. Today, CAN controllers are available from over 20 manufacturers, and CAN is finding applications in other fields, such as medical, aerospace, process control, automation, and so on. This book is written for students, for practising engineers, for hobbyists, and for everyone else who may be interested to learn more about the CAN bus and its applications. The aim of this book is to teach you the basic principles of CAN networks and in addition the development of microcontroller based projects using the CAN bus. In summary, this book enables the reader to: Learn the theory of the CAN bus used in automotive industry; Learn the principles, operation, and programming of microcontrollers; Design complete microcontroller based projects using the C language; Develop complete real CAN bus projects using microcontrollers; Learn the principles of OBD systems used to debug vehicle electronics. You will learn how to design microcontroller based CAN bus nodes, build a CAN bus, develop high-level programs, and then exchange data in real-time over the bus. You will also learn how to build microcontroller hardware and interface it to LEDs, LCDs, and A/D converters. The book assumes that the reader has some knowledge on basic electronics. Knowledge of the C programming language will be useful in later chapters of the book, and familiarity with at least one member of the PIC series of microcontrollers will be an advantage, especially if the reader intends to develop microcontroller based projects using the CAN bus. The CD contains a special demo version of the mikroC compiler which supports the key microcontrollers including: PIC, dsPIC, PIC24, PIC32 and AVR. This special version additionally features an advanced CAN library of intuitive and simple-to-use functions to encourage programming with easy and comfortable development of CAN networks. This book, written by a leading expert in the field of Controller Area Network (CAN) technologies, represents the perfect guide to implementing an SAE J1939 protocol stack for embedded systems. The book is filled with numerous C/C++ code examples and valuable documentation of the resulting J1939 vehicle network data traffic. It explains in great detail the inner workings of the protocol through designing and transmitting J1939 data frames, receiving and processing J1939 data frames, and simulating J1939 ECUs (Electronic Control Units). Other Arduino sketches (software projects) include a J1939 network scanner, and a simple SAE J1939 to USB Gateway application with associated Windows GUI (Visual Studio C# project). The collection of sketches is concluded by the ARD1939 project, a fully functional SAE J1939 protocol stack for the Arduino Uno and Mega 2560. As an added value, the included proof of concept explains (by means of code examples and bus traffic recordings) the details of the Transport Protocol (TP) according to SAE J1939/21 (BAM Session, RTS/CTS Session) and the Address Claim Procedure according to SAE J1939/81. In combination with the low-cost and high-level user-friendliness approach of the Arduino environment, this book represents the ideal platform to learning and implementing embedded applications with the SAE J1939 protocol stack. Modern vehicles have electronic control units (ECUs) to control various subsystems such as the engine, brakes, steering, air conditioning, and infotainment. These ECUs (or simply ‘controllers’) are networked together to share information, and output directly measured and calculated data to each other. This in-vehicle network is a data goldmine for improved maintenance, measuring vehicle performance and its subsystems, fleet

management, warranty and legal issues, reliability, durability, and accident reconstruction. The focus of Data Acquisition from HD Vehicles Using J1939 CAN Bus is to guide the reader on how to acquire and correctly interpret data from the in-vehicle network of heavy-duty (HD) vehicles. The reader will learn how to convert messages to scaled engineering parameters, and how to determine the available parameters on HD vehicles, along with their accuracy and update rate. Written by two specialists in this field, Richard (Rick) P. Walter and Eric P. Walter, principals at HEM Data, located in the United States, the book provides a unique road map for the data acquisition user. The authors give a clear and concise description of the CAN protocol plus a review of all 19 parts of the SAE International J1939 standard family. Pertinent standards are illuminated with tables, graphs and examples. Practical applications covered are calculating fuel economy, duty cycle analysis, and capturing intermittent faults. A comparison is made of various diagnostic approaches including OBD-II, HD-OBD and World Wide Harmonized (WWH) OBD. Data Acquisition from HD Vehicles Using J1939 CAN Bus is a must-have reference for those interested to acquire data effectively from the SAE J1939 equipped vehicles. The vast majority of control systems built today are embedded; that is, they rely on built-in, special-purpose digital computers to close their feedback loops. Embedded systems are common in aircraft, factories, chemical processing plants, and even in cars–a single high-end automobile may contain over eighty different computers. The design of embedded controllers and of the intricate, automated communication networks that support them raises many new questions—practical, as well as theoretical—about network protocols, compatibility of operating systems, and ways to maximize the effectiveness of the embedded hardware. This handbook, the first of its kind, provides engineers, computer scientists, mathematicians, and students a broad, comprehensive source of information and technology to address many questions and aspects of embedded and networked control. Separated into six main sections—Fundamentals, Hardware, Software, Theory, Networking, and Applications—this work unifies into a single reference many scattered articles, websites, and specification sheets. Also included are case studies, experiments, and examples that give a multifaceted view of the subject, encompassing computation and communication considerations. While the Arduino is not widely considered an industrial-strength solution, it provides, due to its low price and ease of programming, the perfect prototyping platform for all kinds of Controller Area Network (CAN) applications. This book, written by a leading expert on CAN technologies, guides the reader through the process of acquiring all necessary hardware and software components, the implementation of the CAN driver, and the implementation of programs (Arduino Sketches) to read, send, process, and display data from and to a CAN network. The collection of programming examples cumulates into a full-fledged USB-to-CAN Gateway communicating with a Windows/Linux PC. This book will enable you to achieve CAN functionality literally within only a few hours. Multiplexed networks are essential for the unified, efficient and cost-effective exchange of electronic information within embedded component systems. This is especially important in automotive manufacturing as vehicles become increasingly reliant on robust electronic networks and systems for improved reliability, anti-lock brake systems (ABS), steering, on-board navigation systems, and much more. The latest systems such as X-by-Wire and FlexRay aim to produce faster, fault-tolerant network component interconnects, for state-of-the-art network implementation and safer, more reliable engineering of vehicular systems. This book provides a thorough and comprehensive introduction to automotive multiplexed network buses, covering the technical principles, components, implementation issues and applications. Key features: Presents a thorough coverage of the controller area network (CAN) protocol, including information on physical layers, conformity problems, hardware and software tools, and application layers. Gives a detailed description of the new local interconnect network (LIN) bus, setting out its developments, properties, problems and ways to overcome these. Examines the existing and emerging network buses such as time-triggered CAN (TTCAN), FlexRay and X-by-Wire. Explores the possibilities for linking the various buses that are discussed, explaining how the Fail-Safe-System basis chip (SBC) and other gateways are designed and constructed. Analyses wired and wireless internal and external serial links, including Safe-by-Wire plus, I2C, Media Oriented Systems Transport (MOST), remote keyless entry, tyre pressure monitoring systems (TPMS) and Bluetooth. A valuable guide to embedded systems for a range of applications, Multiplexed Networks for Embedded Systems: CAN, LIN, FlexRay, Safe-by-Wire...is essential reading for electronics engineers and researchers developing electronics for the automotive industry. It is also useful for practising aerospace engineers and other practitioners interested in the application of network technologies, and advanced students taking courses on automotive and embedded system design. This book to offers a hands-on guide to designing, analyzing and debugging a communication infrastructure based on the Controller Area Network (CAN) bus. Although the CAN bus standard is well established and currently used in most automotive systems, as well as avionics, medical systems and other devices, its features are not fully understood by most developers, who tend to misuse the network. This results in lost opportunities for better efficiency and performance. These authors offer a comprehensive range of architectural solutions and domains of analysis. It also provides formal models and analytical results, with thorough discussion of their applicability, so that it serves as an invaluable reference for researchers and students, as well as practicing engineers. Modern cars are more computerized than ever. Infotainment and navigation systems, Wi-Fi, automatic software updates, and other innovations aim to make driving more convenient. But vehicle technologies haven’t kept pace with today’s more hostile security environment, leaving millions vulnerable to attack. The Car Hacker’s Handbook will give you a deeper understanding of the computer systems and embedded software in modern vehicles. It begins by examining vulnerabilities and providing detailed explanations of communications over the CAN bus and between devices and systems. Then, once you have an understanding of a vehicle’s communication network, you’ll learn how to intercept data and perform specific hacks to track vehicles, unlock doors, glitch engines, flood communication, and more. With a focus on low-cost, open source hacking tools such as Metasploit, Wireshark, Kayak, can-utils, and ChipWhisperer, The Car Hacker’s Handbook will show you how to: –Build an accurate threat model for your vehicle –Reverse engineer the CAN bus to fake engine signals –Exploit vulnerabilities in diagnostic and data-logging systems –Hack the ECU and other firmware and embedded systems –Feed exploits through infotainment and vehicle-to-vehicle communication systems –Override factory settings with performance-tuning techniques –Build physical and virtual test benches to try out exploits safely If you’re curious about automotive security and have the urge to hack a two-ton computer, make The Car Hacker’s Handbook your first stop. Learn how automotive Ethernet is revolutionizing in-car networking from the experts at the core of its development. Providing an in-depth account of automotive Ethernet, from its background and development, to its future prospects, this book is ideal for industry professionals and academics alike. The MSP430 microcontroller family offers ultra-low power mixed signal, 16-bit architecture that is perfect for wireless low-power industrial and portable medical applications. This book begins with an overview of embedded systems and microcontrollers followed by a comprehensive in-depth look at the MSP430. The coverage included a tour of the microcontroller's architecture and functionality along with a review of the development environment. Start using the MSP430 armed with a complete understanding of the microcontroller and what you need to get the microcontroller up and running! Details C and assembly language for the MSP430 Companion Web site contains a development kit Full coverage is given to the MSP430 instruction set, and sigma-delta analog-digital converters and timers The University of North Carolina Charlotte is provided with a Honda Four Trax Ranch ATV by Zapata Engineering (a small business firm located in Charlotte, NC) which is intended to tow a trailer of ground sensing equipment. The mechanical control system of the all-terrain vehicle (ATV) is converted to an electronic control system and is interfaced to a wireless radio system. The control system of the ATV is designed to run autonomously with the help of LIDAR, GPS and camera and can also be controlled over the wireless radio system. In order to improve the control system design and reduce the wiring, a Controller Area Network (CAN) control system has been implemented which is very flexible and reliable. A CAN control system contains electronic control units (ECU) which communicate over CAN protocol. CAN protocol is a serial communication protocol which is internationally standardized by ISO and it creates a two line differential bus for communication. It is a widely used real time communication protocol designed mainly for in vehicle networking but also gained popularity in many embedded applications. This thesis presents a design and implementation of a prototype CAN control system for the ATV with the LIDAR, GPS and IMU connected to the ECU. Welcome to ICOIN 2005,the International Conference on

Information Netwo- ing, held at Ramada Plaza Jeju Hotel, Jeju Island, Korea during January 31–February2,2005.ICOIN2005followedthesuccessofpreviousconferences. Since 1986, the conference has provided a technical forum for various issues in inf- mation networking. The theme of each conference re?ects the historic events in the computer communication industry. (Please refer to www.icoin2005.or.kr for details.) The theme of ICOIN 2004, “Convergence in Broadband and Mobile Networking,” was used again for ICOIN 2005 since we believed it was ongoing. This year we received 427 submissions in total, which came from 22 co- tries. Upon submission, authors were asked to select one of the categories listed in the Call for Papers. The most popular category chosen was network se- rity, followed by mobile networks and wireless LANs. Other areas with strong showings included QoS and resource management, ad hoc and sensor networks, and wireless multimedia systems. From the outset, we could see where recent research interest lay and could make sure that the theme was still going in the right direction. Time-Triggered Communication helps readers build an understanding of the conceptual foundation, operation, and application of time-triggered communication, which is widely used for embedded systems in a diverse range of industries. This book assembles contributions from experts that examine the differences and commonalities of the most significant protocols including: TTP, FlexRay, TTEthernet, SAFEbus, TTCAN, and LIN. Covering the spectrum, from low-cost time-triggered fieldbus networks to ultra-reliable time-triggered networks used for safety-critical applications, the authors illustrate the inherent benefits of time-triggered communication in terms of predictability, complexity management, fault-tolerance, and analytical dependability modeling, which are key aspects of safety-critical systems. Examples covered include FlexRay in cars, TTP in railway and avionic systems, and TTEthernet in aerospace applications. Illustrating key concepts based on real-world industrial applications, this book: Details the underlying concepts and principles of time-triggered communication Explores the properties of a time-triggered communication system, contrasting its strengths and weaknesses Focuses on the core algorithms applied in many systems, including those used for clock synchronization, startup, membership, and fault isolation Describes the protocols that incorporate presented algorithms Covers tooling requirements and solutions for system integration, including scheduling The information in this book is extremely useful to industry leaders who design and manufacture products with distributed embedded systems based on time-triggered communication. It also benefits suppliers of embedded components or development tools used in this area. As an educational tool, this material can be used to teach students and working professionals in areas including embedded systems, computer networks, system architectures, dependability, real-time systems, and automotive, avionics, and industrial control systems. The superabundance of data that is created by today's businesses is making storage a strategic investment priority for companies of all sizes. As storage takes precedence, the following major initiatives emerge: Flatten and converge your network: IBM® takes an open, standards-based approach to implement the latest advances in the flat, converged data center network designs of today. IBM Storage solutions enable clients to deploy a high-speed, low-latency Unified Fabric Architecture. Optimize and automate virtualization: Advanced virtualization awareness reduces the cost and complexity of deploying physical and virtual data center infrastructure. Simplify management: IBM data center networks are easy to deploy, maintain, scale, and virtualize, delivering the foundation of consolidated operations for dynamic infrastructure management. Storage is no longer an afterthought. Too much is at stake. Companies are searching for more ways to efficiently manage expanding volumes of data, and to make that data accessible throughout the enterprise. This demand is propelling the move of storage into the network. Also, the increasing complexity of managing large numbers of storage devices and vast amounts of data is driving greater business value into software and services. With current estimates of the amount of data to be managed and made available increasing at 60% each year, this outlook is where a storage area network (SAN) enters the arena. SANs are the leading storage infrastructure for the global economy of today. SANs offer simplified storage management, scalability, flexibility, and availability; and improved data access, movement, and backup. Welcome to the cognitive era. The smarter data center with the improved economics of IT can be achieved by connecting servers and storage with a high-speed and intelligent network fabric. A smarter data center that hosts IBM Storage solutions can provide an environment that is smarter, faster, greener, open, and easy to manage. This IBM® Redbooks® publication provides an introduction to SAN and Ethernet networking, and how these networks help to achieve a smarter data center. This book is intended for people who are not very familiar with IT, or who are just starting out in the IT world. How a protocol born in the 1970's has stayed relevant in automation for over 30 years. -- Taken from cover. This book addresses the various challenges and open questions relating to CAN communication networks. Opening with a short introduction into the fundamentals of CAN, the book then examines the problems and solutions for the physical layout of networks, including EMC issues and topology layout. Additionally, a discussion of quality issues with a particular focus on test techniques is presented. Each chapter features a collection of illuminating insights and detailed technical information supplied by a selection of internationally-regarded experts from industry and academia. Features: presents thorough coverage of architectures, implementations and application of CAN transceiver, data link layer and so-called higher layer software; explains CAN EMC characteristics and countermeasures, as well as how to design CAN networks; demonstrates how to practically apply and test CAN systems; includes examples of real networks from diverse applications in automotive engineering, avionics, and home heating technology.

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